



A Random Dot Product Graph Model for Weighted and Directed Networks

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Random dot product graphs

- Consider a **latent space** $\mathcal{X}_d \subset \mathbb{R}^d$ such that for all

$$\mathbf{x}, \mathbf{y} \in \mathcal{X}_d \quad \Rightarrow \quad \mathbf{x}^\top \mathbf{y} \in [0, 1]$$

\Rightarrow Inner-product distribution $F : \mathcal{X}_d \mapsto [0, 1]$

- **Random dot product graphs (RDPGs)** are defined as follows:

$$\mathbf{x}_1, \dots, \mathbf{x}_{N_v} \stackrel{\text{i.i.d.}}{\sim} F,$$
$$A_{ij} \mid \mathbf{x}_i, \mathbf{x}_j \sim \text{Bernoulli}(\mathbf{x}_i^\top \mathbf{x}_j)$$

for $1 \leq i, j \leq N_v$, where $A_{ij} = A_{ji}$ and $A_{ii} \equiv 0$

- A particularly tractable **latent position random graph model**

\Rightarrow Vertex positions $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_{N_v}]^\top \in \mathbb{R}^{N_v \times d}$

S. J. Young and E. R. Scheinerman, “Random dot product graph models for social networks,” *WAW*, 2007



Estimation of latent positions

- **Q:** Given $G = (V, E)$ from an RDPG, find the ‘best’ $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_{N_v}]^\top$?
- MLE is well motivated but it is intractable for large N_v

$$\hat{\mathbf{X}}_{ML} = \operatorname{argmax}_{\mathbf{X}} \prod_{i < j} (\mathbf{x}_i^\top \mathbf{x}_j)^{A_{ij}} (1 - \mathbf{x}_i^\top \mathbf{x}_j)^{1 - A_{ij}}$$



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- Instead, let $P_{ij} = \mathbb{P}((i, j) \in \mathcal{E})$ and define $\mathbf{P} = [P_{ij}] \in [0, 1]^{N_v \times N_v}$
 - ⇒ RDPG model specifies that $\mathbf{P} = \mathbf{X}\mathbf{X}^\top$
 - ⇒ **Key:** Observed \mathbf{A} is a noisy realization of \mathbf{P} ($\mathbb{E}\{\mathbf{A}\} = \mathbf{P}$)
- Suggests a **LS regression** approach to find \mathbf{X} s.t. $\mathbf{X}\mathbf{X}^\top \approx \mathbf{A}$

$$\hat{\mathbf{X}}_{LS} = \operatorname{argmin}_{\mathbf{X}} \|\mathbf{X}\mathbf{X}^\top - \mathbf{A}\|_F^2$$

A. Athreya et al, “Statistical inference on random dot product graphs: A survey,” *JMLR*, 2018



Adjacency spectral embedding

- Since \mathbf{A} is real and symmetric, can decompose it as $\mathbf{A} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^\top$
 - $\mathbf{U} = [\mathbf{u}_1, \dots, \mathbf{u}_{N_v}]$ is the orthogonal matrix of eigenvectors
 - $\mathbf{\Lambda} = \text{diag}(\lambda_1, \dots, \lambda_{N_v})$, with eigenvalues $\lambda_1 \geq \dots \geq \lambda_{N_v}$



Adjacency spectral embedding

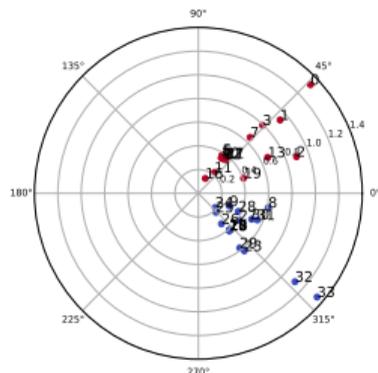
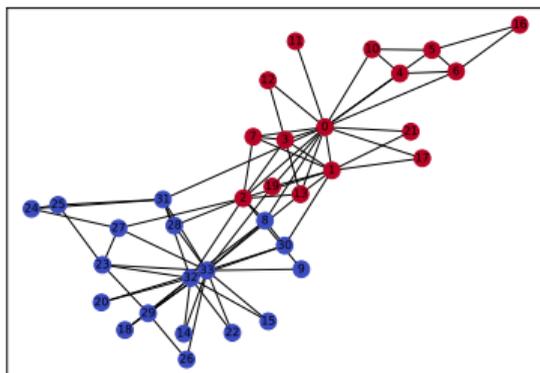
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- Define $\hat{\mathbf{\Lambda}} = \text{diag}(\lambda_1^+, \dots, \lambda_d^+)$ and $\hat{\mathbf{U}} = [\mathbf{u}_1, \dots, \mathbf{u}_d]$ ($\lambda^+ := \max(0, \lambda)$)
- Best rank- d , positive semi-definite (PSD) approximation of \mathbf{A} is $\hat{\mathbf{U}}\hat{\mathbf{\Lambda}}\hat{\mathbf{U}}^\top$
 \Rightarrow Adjacency spectral embedding (ASE) is $\hat{\mathbf{X}}_{LS} = \hat{\mathbf{U}}\hat{\mathbf{\Lambda}}^{1/2}$ since

$$\mathbf{A} \approx \hat{\mathbf{U}}\hat{\mathbf{\Lambda}}\hat{\mathbf{U}}^\top = \hat{\mathbf{U}}\hat{\mathbf{\Lambda}}^{1/2}\hat{\mathbf{\Lambda}}^{1/2}\hat{\mathbf{U}}^\top = \hat{\mathbf{X}}_{LS}\hat{\mathbf{X}}_{LS}^\top$$



Interpretability of the embeddings

- **Ex:** Zachary's karate club graph with $N_v = 34$, $N_e = 78$ (left)



- Node embeddings (rows of $\hat{\mathbf{X}}_{LS}$) for $d = 2$ (right)
 - Club's administrator ($i = 0$) and instructor ($j = 33$) are orthogonal
- Interpretability of embeddings a valuable asset for RDPGs
 - ⇒ **Vector magnitudes** indicate how well connected nodes are
 - ⇒ **Vector angles** indicate nodes' affinity



Weighted graphs

■ **Q:** Can we extend the RDPG model to the weighted case?

■ **Idea** latent positions related to the moment generating function (MGF) of weights ω_{ij}

⇒ **Weighted RDPG:** Each node now has a **sequence of vectors** $(\mathbf{x}_i[k] \in \mathbb{R}^{d_k})_{k \in \mathbb{N}}$ where

$$\mathbb{E}[\omega_{ij}^k] = \mathbf{x}_i[k]^\top \mathbf{x}_j[k]$$

⇒ Weights are independently drawn from distributions with MGF

$$\mathbb{E}\{e^{t\omega_{ij}}\} = \sum_{k=0}^{\infty} \frac{t^k \mathbb{E}\{\omega_{ij}^k\}}{k!} = \sum_{k=0}^{\infty} \frac{t^k \mathbf{x}_i[k]^\top \mathbf{x}_j[k]}{k!}$$



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■ We now have a sequence of matrices $\mathbf{X}[k] = [\mathbf{x}_1[k], \dots, \mathbf{x}_{N_v}[k]]^\top$ such that

$$\mathbb{E}\left\{ \underbrace{\mathbf{A} \circ \mathbf{A} \circ \dots \circ \mathbf{A}}_{k \text{ times}} \right\} = \mathbb{E}\left\{ \mathbf{A}^{(k)} \right\} := \mathbf{M}[k] = \mathbf{X}[k] \mathbf{X}[k]^\top$$



Weighted RDPG

Advantages

- ✓ Backwards compatibility: vanilla RDPG is recovered by setting $\mathbf{x}_i[k] = \mathbf{x}_i$ for all $k > 0$
- ✓ Flexible way of specifying a distribution per edge
 - Accommodates discrete and/or continuous distribution
 - Prior art relied on **fixed, known, parametric** distribution $F(A_{ij}; \boldsymbol{\theta} = \{\mathbf{x}_i^\top[k]\mathbf{x}_j[k]\}_{k=1}^K)$

R. Tang et al, “Robust estimation from multiple graphs under gross error contamination”,
arXiv:1707.03487, 2017

D. DeFord et al, “A Random Dot Product Model for Weighted Networks”, arXiv:1611.02530, 2016



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- ✓ Sparsity pattern of $\mathbf{A}^{(k)}$ is maintained for all k
- ✓ Observation $\mathbf{A}^{(k)}$ is a noisy realization of $\mathbf{M}[k]$
 \Rightarrow **Inference** of the embedding sequence $(\hat{\mathbf{X}}[k])$ via the ASE of $\mathbf{A}^{(k)}$

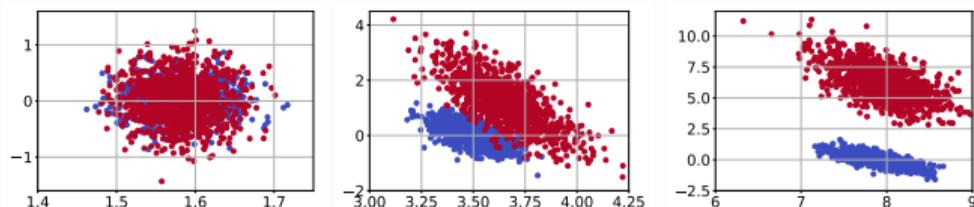
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Weighted RDPG: Discriminative power

- **Ex:** $Q = 2$ block weighted SBM graph G with $N_v = 2000$, edges present w.p. $p = 0.5$
 \Rightarrow Weights $A_{ij} \sim \mathcal{N}(5, 0.1)$ except among nodes $i > 1000$, where $A_{ij} \sim \text{Poisson}(5)$



- ASE estimates $\hat{\mathbf{x}}_i[k]$ for $k = 1$ (left), $k = 2$ (center), $k = 3$ (right), where $d = 2$
 - Indistinguishable for $k = 1$, since $\hat{\mathbf{x}}_i[1]$ are centered around $(\sqrt{\mu p}, 0) = (\sqrt{\lambda p}, 0) \approx (1.58, 0)$
 - Noise hinders discriminability for $k = 2$, even though

$$\mathbf{x}_i[2] = \begin{cases} (\sqrt{p(\mu^2 + \sigma^2)}, 0) \approx (3.55, 0) & i \leq 1000, \\ (\sqrt{p(\mu^2 + \sigma^2)}, \sqrt{p(\lambda^2 + \lambda - (\mu^2 + \sigma^2))}) \approx (3.55, 1.58) & i > 1000 \end{cases}$$

- Skewness kicks in for $k = 3$ and group separation is apparent



Weighted and Directed Graphs

- So far, matrix $\mathbf{M}[k]$ is **restricted** to be
 - ✗ Positive semi-definitive: what about heterophilous behaviour?
 - ✗ Symmetric: what about directed graphs?



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- ✗ Symmetric: what about directed graphs?

■ **Extension to digraphs**

- Each node has an associated sequence $\mathbf{x}_i[k]$ – now in \mathbb{R}^{2d}
- Or two vectors: $\mathbf{x}_i^l[k]$ and $\mathbf{x}_i^r[k]$ (first and last d entries of \mathbf{x}_i)

■ Model:

$$\mathbb{E} \left\{ \mathbf{A}^{(k)} \right\} := \mathbf{M}[k] = \mathbf{X}^l[k] \mathbf{X}^r[k]^\top \quad (1)$$



Weighted and Directed RDPG

■ Inference:

- $\mathbf{M}[k] = \mathbb{E} \left\{ \mathbf{A}^{(k)} \right\}$ still holds
- \Rightarrow Seek $\{\hat{\mathbf{X}}^l[k], \hat{\mathbf{X}}^r[k]\}$ s.t. $\hat{\mathbf{X}}^l[k]\hat{\mathbf{X}}^r[k]^\top$ is the best rank- d approximation of $\mathbf{A}^{(k)}$



Weighted and Directed RDPG

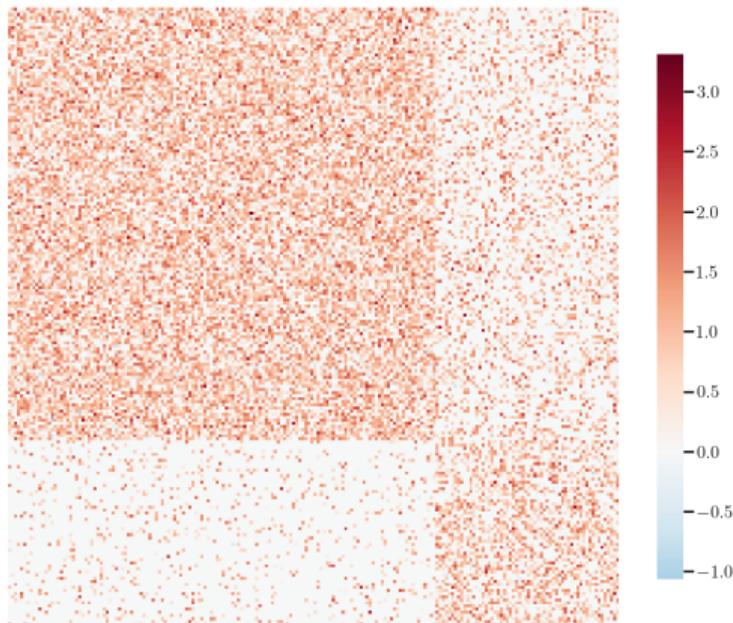
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- SVD: $\mathbf{A}^{(k)} = \mathbf{U}[k]\mathbf{D}[k]\mathbf{V}[k]^\top$
⇒ $\hat{\mathbf{X}}^l[k] = \hat{\mathbf{U}}[k]\hat{\mathbf{D}}[k]^{1/2}$ and $\hat{\mathbf{X}}^r[k] = \hat{\mathbf{V}}[k]\hat{\mathbf{D}}[k]^{1/2}$
- What about backwards compatibility? Enforced by the choice of $\hat{\mathbf{D}}[k]^{1/2}$
 - $\mathbf{M}[k]$ is symmetric $\Leftrightarrow \mathbf{X}^l[k] = \mathbf{X}^r[k]$



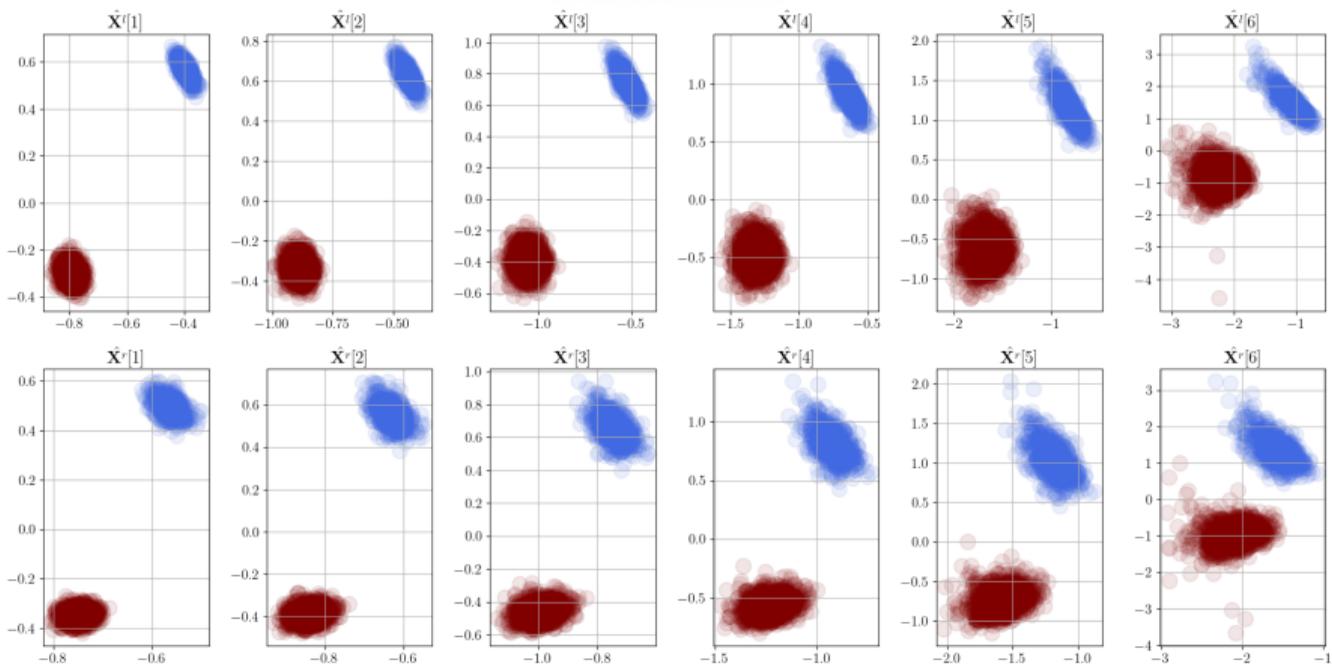
Embedding a Weighted SBM Graph

- A weighted SBM graph G with $N_v = 2000$, number of classes $Q = 2$, inter-class connection probability matrix $\mathbf{\Pi} = \begin{pmatrix} 0.7 & 0.3 \\ 0.1 & 0.5 \end{pmatrix}$ and weights $A_{ij} \sim \mathcal{N}(1, 0.5)$



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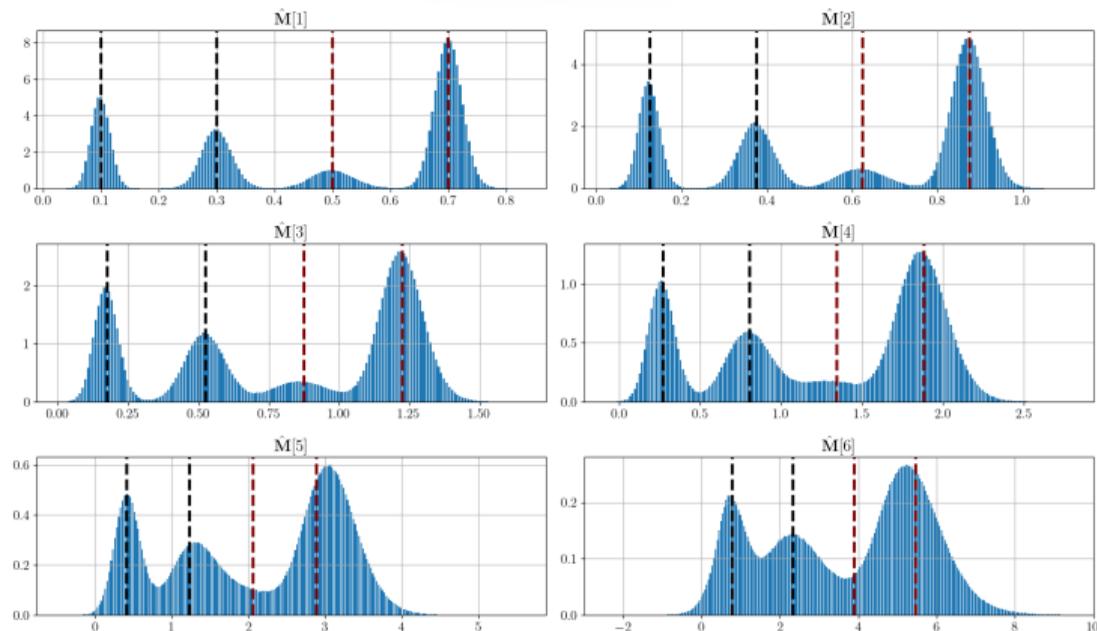
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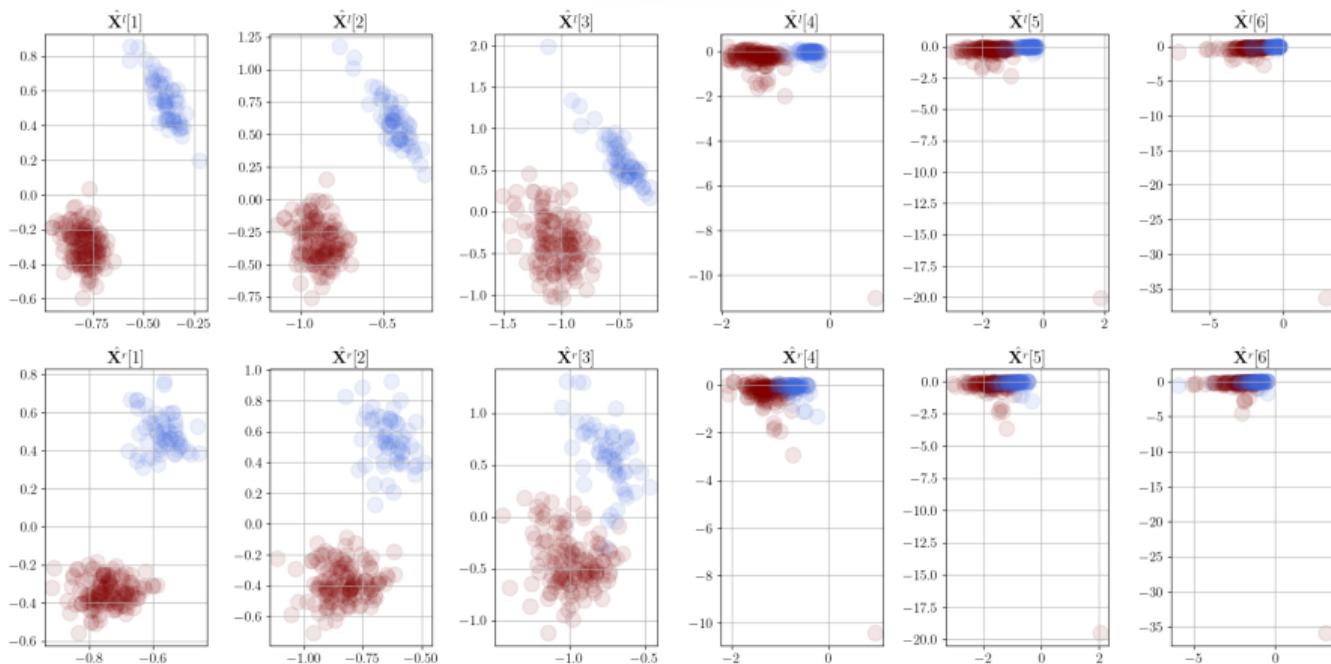
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- $\hat{\mathbf{X}}^l[k]$ and $\hat{\mathbf{X}}^r[k]$ for $k = 1, \dots, 6$ can reconstruct accurate values of $\hat{\mathbf{M}}[k]$ up to $k \approx 4$



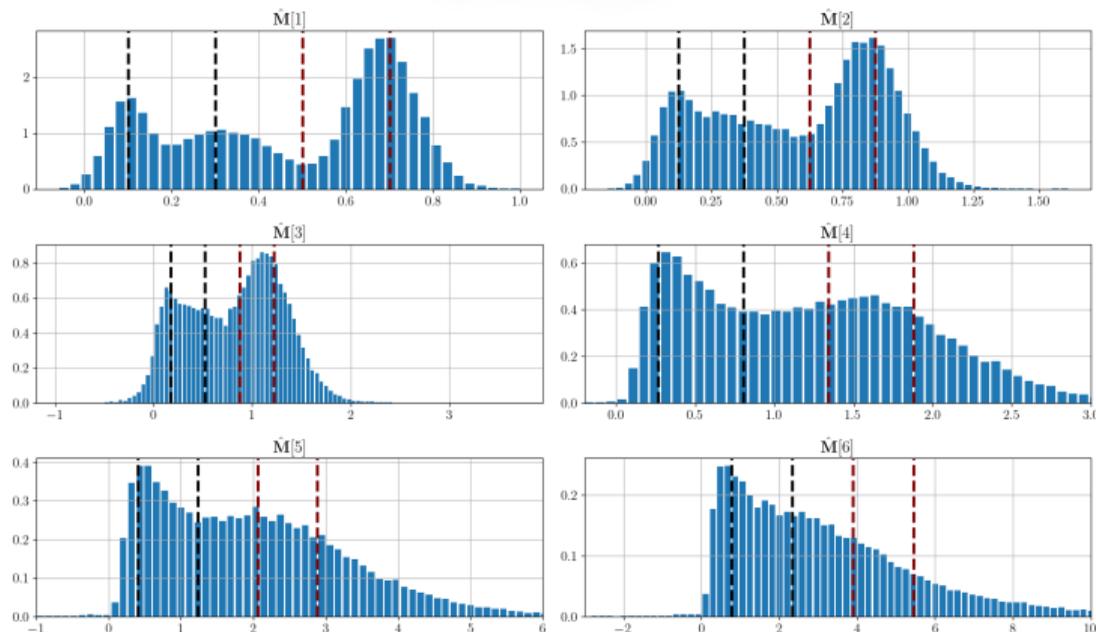
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 - $\hat{\mathbf{X}}^l[k]$ and $\hat{\mathbf{X}}^r[k]$ for $k = 1, \dots, 6$ reconstructs accurate values of $\hat{\mathbf{M}}[k]$ up to $k \approx 2$ (somewhat)



Consistency of ASE for WD-RDPG

Theorem (Consistency): Let $\mathbf{B} \in \mathbb{R}^{N \times N}$ be a random matrix such that $\{B_{ii}\} = 0$, and $\{B_{ij}\}_{i \neq j}$ are bounded and independent with $\mathbb{E}[B_{ij}] = E_{ij}$, $\mathbf{E} = \mathbf{X}\mathbf{Y}^\top$ for fixed $\mathbf{X}, \mathbf{Y} \in \mathbb{R}^{N \times d}$.

Assume $\text{rank}(\mathbf{E}) = d$ and that the singular values of \mathbf{E} $\sigma_1 > \sigma_2 > \dots > \sigma_d > 0$ are such that $\min_{i \neq j} |\sigma_i - \sigma_j| > \delta N$ and $\sigma_d > \delta N$ for some $\delta > 0$. Let $\hat{\mathbf{X}}, \hat{\mathbf{Y}} \in \mathbb{R}^{N \times d}$ be the ASE of \mathbf{B} . Then, there almost always exist an invertible matrix $\mathbf{W} \in \mathbb{R}^{d \times d}$ such that, for all $i \in \{1, \dots, N\}$ and all $\gamma < 1$,

$$\mathbb{P} \left[\|\hat{\mathbf{X}}\mathbf{W} - \mathbf{X}\|_2^2 > N^{-\gamma} \right] = o(N^{\gamma-1} \log N)$$

$$\mathbb{P} \left[\|\hat{\mathbf{Y}}\mathbf{W}^{-\top} - \mathbf{Y}\|_2^2 > N^{-\gamma} \right] = o(N^{\gamma-1} \log N)$$

where \mathbf{C}_i is the i -th row of matrix \mathbf{C} .



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- For each fixed k , we let $\mathbf{B} = \mathbf{A}^{(k)}$ to ensure consistency of the ASE to $\mathbf{X}^l[k], \mathbf{X}^r[k]$



Asymptotic Normality of ASE for WD-RDPG

Theorem (Central Limit Theorem): Let F be a weighted, directed, inner-product distribution. Assume \mathbf{B} and \mathbf{E} as before, only now $\mathbb{E}[B_{ij}|\mathbf{X}, \mathbf{Y}] = E_{ij}$, and $\mathbf{X}, \mathbf{Y} \sim F$. Then there almost always exist a sequence of invertible matrices $\mathbf{W}_N \in \mathbb{R}^{d \times d}$ such that, for all $i \in \{1, \dots, N\}$ and all $\mathbf{z} \in \mathbb{R}^d$:

$$\lim_{N \rightarrow \infty} \mathbb{P} \left[N^{1/2}(\hat{\mathbf{X}}\mathbf{W}_N - \mathbf{X})_i \leq \mathbf{z} \right] = \int_{\text{supp } F} \Phi(\mathbf{z}, \boldsymbol{\Sigma}_{\mathbf{X}}(\mathbf{x})) dF(\mathbf{x})$$

$$\lim_{N \rightarrow \infty} \mathbb{P} \left[N^{1/2}(\hat{\mathbf{Y}}\mathbf{W}_N^{-\top} - \mathbf{Y})_i \leq \mathbf{z} \right] = \int_{\text{supp } F} \Phi(\mathbf{z}, \boldsymbol{\Sigma}_{\mathbf{Y}}(\mathbf{y})) dF(\mathbf{y})$$

where $\Phi(\mathbf{z}, \boldsymbol{\Sigma})$ is zero-mean multivariate normal with covariance matrix $\boldsymbol{\Sigma}$, and

$$\boldsymbol{\Sigma}_{\mathbf{X}}(\mathbf{x}) = \boldsymbol{\Delta}_{\mathbf{X}}^{-1} \mathbb{E} \left[(\mathbf{x}^\top \mathbf{X}_1 - (\mathbf{x}^\top \mathbf{X}_1)^2) \mathbf{X}_1 \mathbf{X}_1^\top \right] \boldsymbol{\Delta}_{\mathbf{X}}^{-1}, \quad \boldsymbol{\Delta}_{\mathbf{X}} = \mathbb{E} \left[\mathbf{X}_1 \mathbf{X}_1^\top \right]$$

$$\boldsymbol{\Sigma}_{\mathbf{Y}}(\mathbf{y}) = \boldsymbol{\Delta}_{\mathbf{Y}}^{-1} \mathbb{E} \left[(\mathbf{y}^\top \mathbf{Y}_1 - (\mathbf{y}^\top \mathbf{Y}_1)^2) \mathbf{Y}_1 \mathbf{Y}_1^\top \right] \boldsymbol{\Delta}_{\mathbf{Y}}^{-1}, \quad \boldsymbol{\Delta}_{\mathbf{Y}} = \mathbb{E} \left[\mathbf{Y}_1 \mathbf{Y}_1^\top \right]$$



Real-life dataset (I): UN roll calls

- For each roll call in the UN General Assembly, members vote ‘Yes’, ‘No’ or ‘Abstain’.
 - ‘Abstain’ is frequently used as another level of agreement with the roll call
- ⇒ Consider the bipartite digraph for 2003, where
- Nodes correspond to member countries and roll calls,
 - Edge weight is either 1 (**affirmative** vote), -1 (**negative**) or 0 (**abstain** or absent).



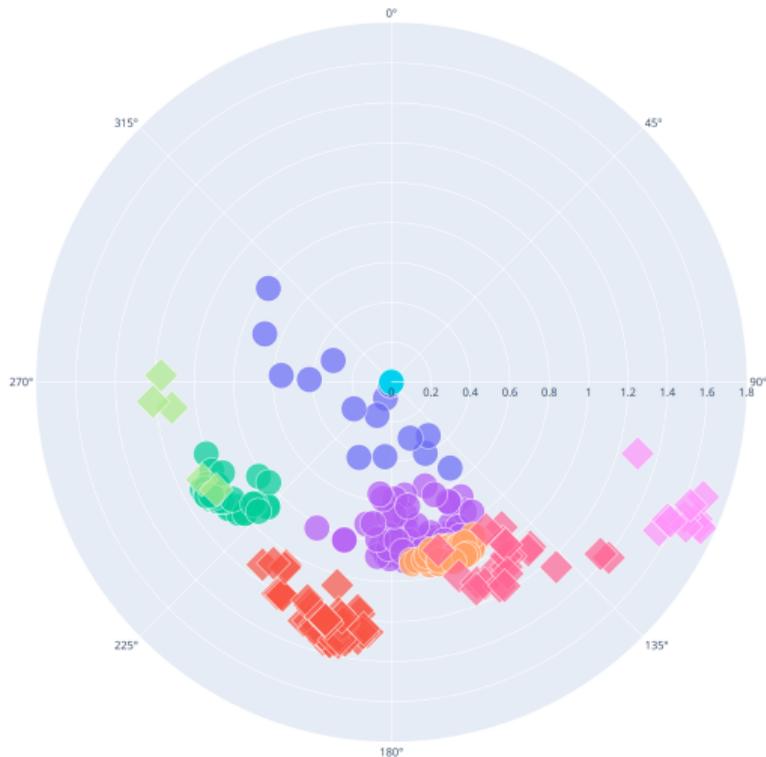
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 - Each country has a probability distribution (p_{-1}, p_0, p_1) for each roll call
- **Q:** What can we learn by visualizing the embeddings? Note that
 - $X_l[k] = 0$ for roll calls (roll calls do not vote)
 - $X_r[k] = 0$ for countries (countries are not voted)



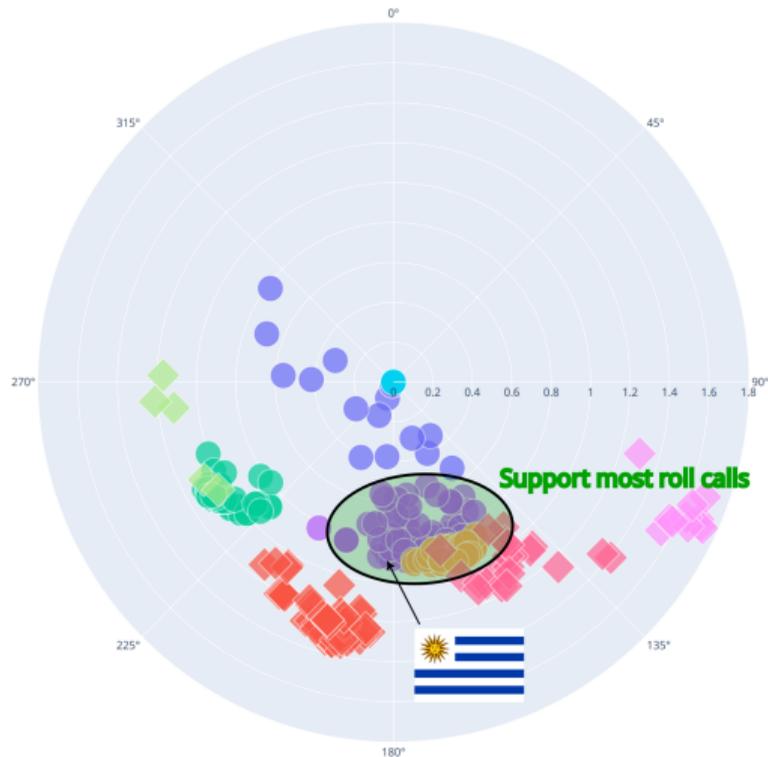
Real-life dataset (I): UN roll calls - Interpretability

- $k = 1$ and $d = 2$. Countries (●) and roll calls (◆) are colored using a GMM clustering



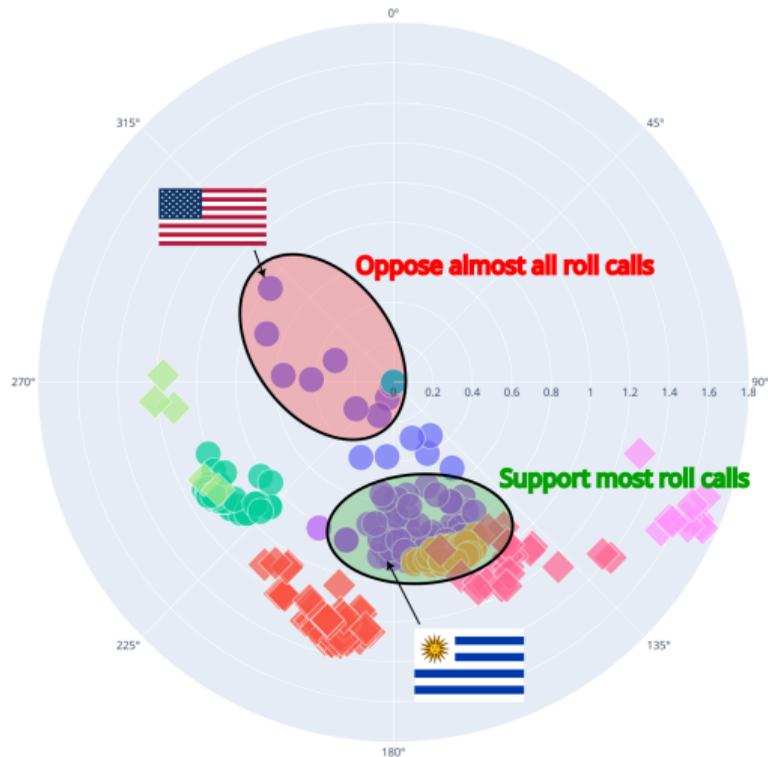
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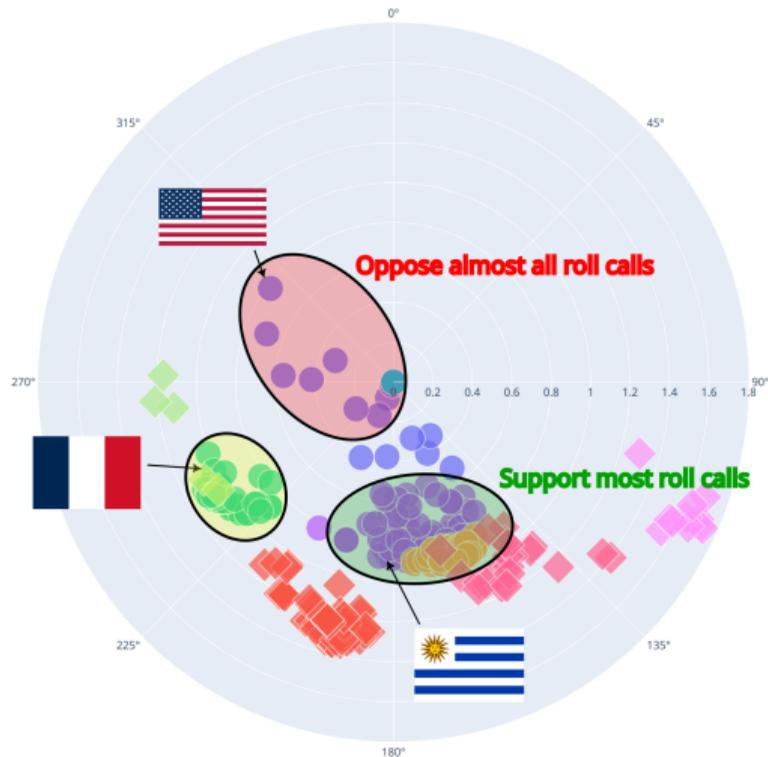
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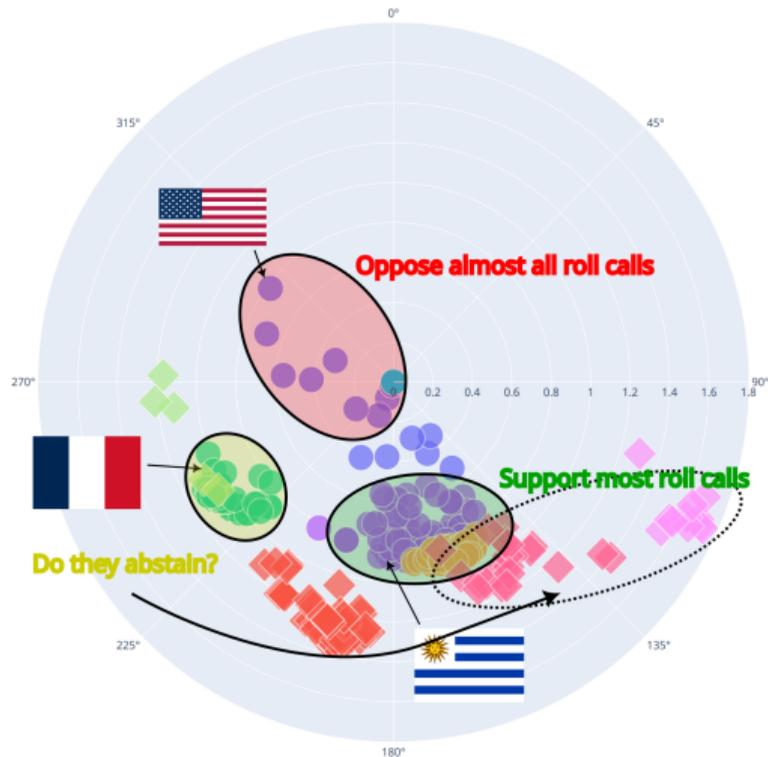
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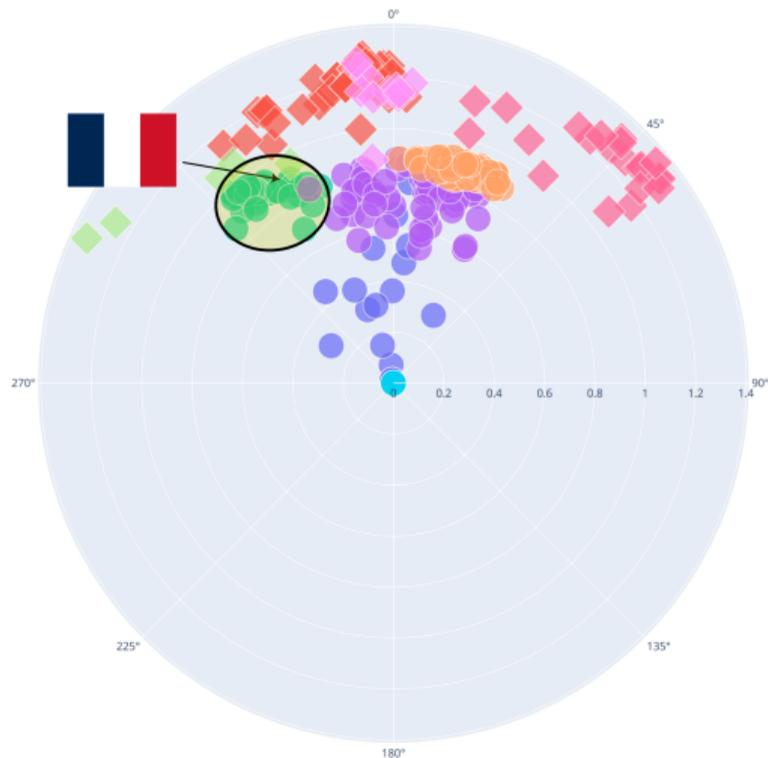
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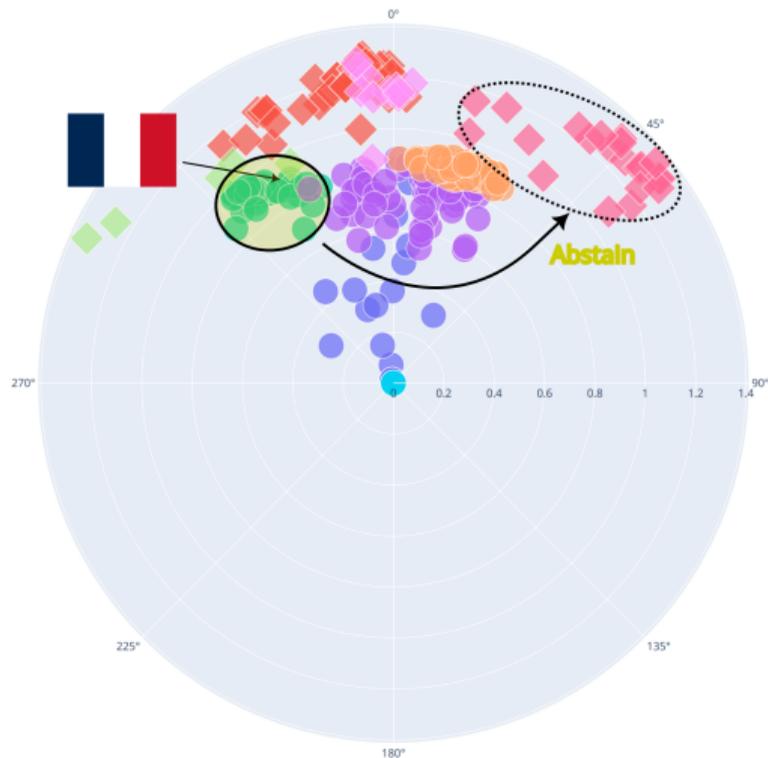
Real-life dataset (I): UN roll calls - Interpretability

■ $k = 2$ and $d = 2$. Countries (●) and roll calls (◆) are colored using a GMM clustering



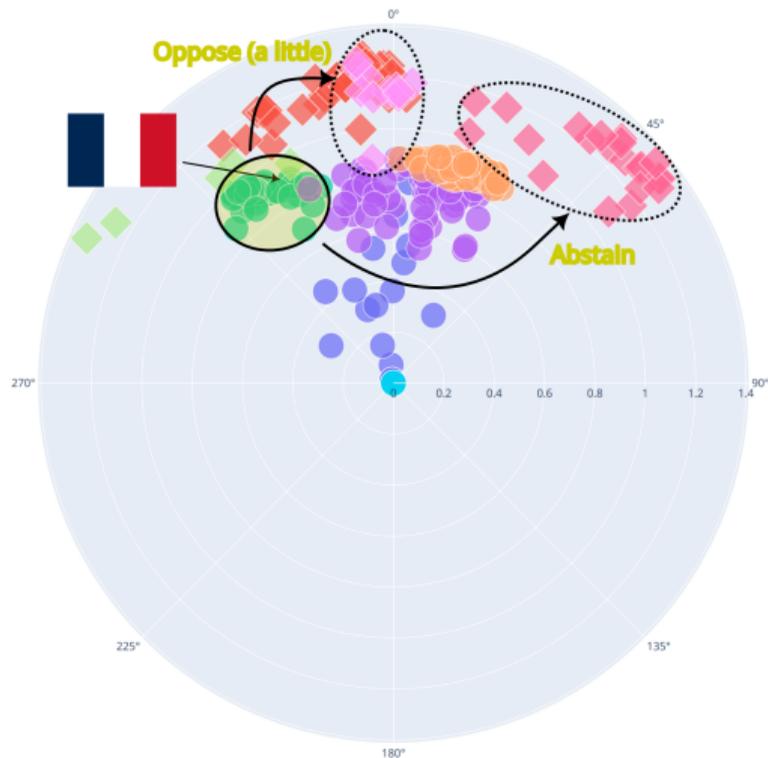
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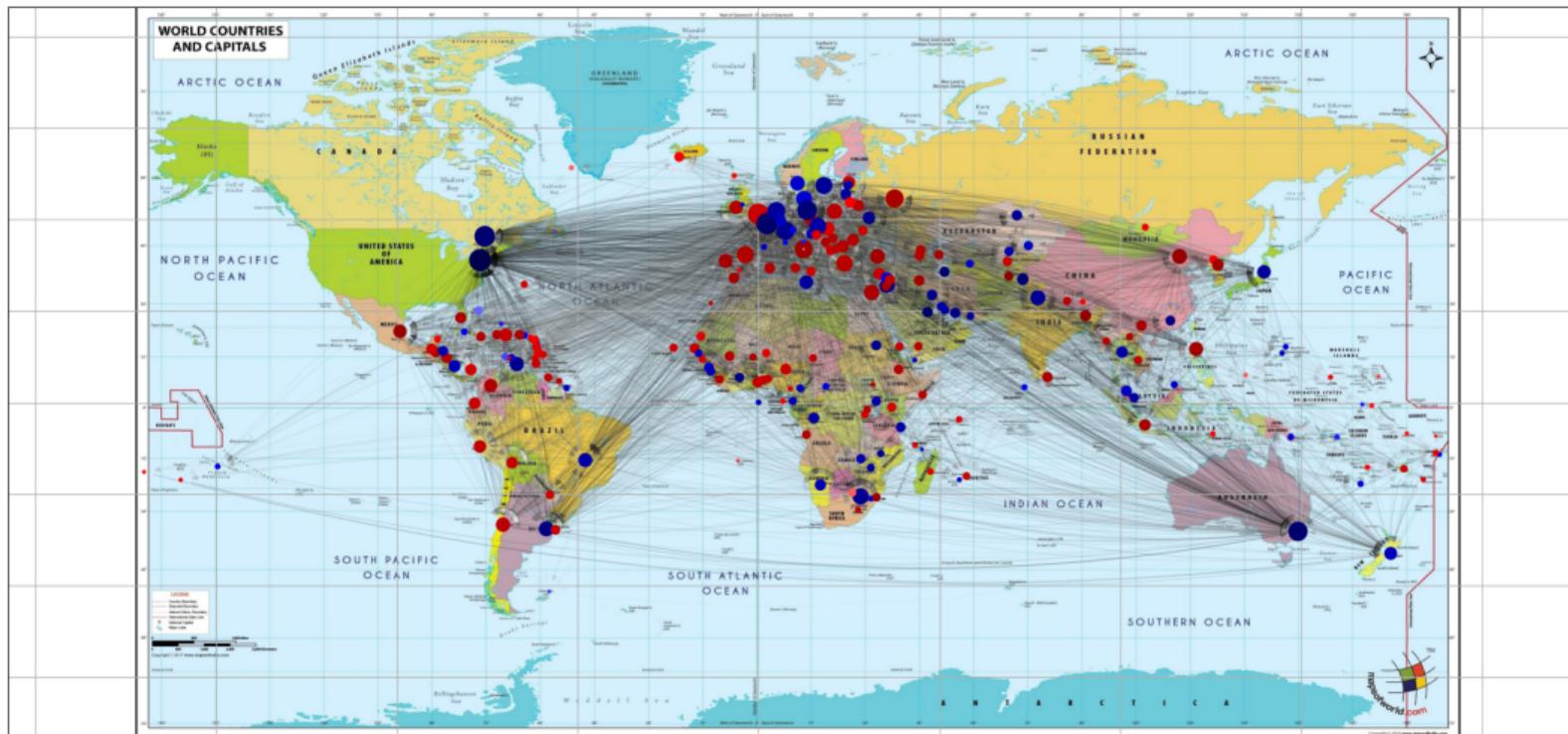
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Real-life dataset (II): UN migration data

■ Migration between countries in 1990 (based on UN data)

- Nodes: size indicative of total degree, net balance is **positive** or **negative**
- Edge thickness indicative of total flow



Real-life dataset (II): UN migration data - Graph Generation

■ How can we generate similar graphs?

⇒ WD-RDPG for **graph generation**

■ **Problem statement:** Generate \mathbf{A} such that, for $1 \leq i, j \leq N$, A_{ij} follows a distribution whose first $K + 1$ moments are $\hat{\mathbf{x}}_i^l[k]^\top \hat{\mathbf{x}}_j^r[k] = \mu_k$ for $k = 0, 1, \dots, K$.



Real-life dataset (II): UN migration data - Graph Generation

- How can we generate similar graphs?

⇒ WD-RDPG for **graph generation**

- **Problem statement:** Generate \mathbf{A} such that, for $1 \leq i, j \leq N$, A_{ij} follows a distribution whose first $K + 1$ moments are $\hat{\mathbf{x}}_i^l[k]^\top \hat{\mathbf{x}}_j^r[k] = \mu_k$ for $k = 0, 1, \dots, K$.

- Today I'll discuss the **discrete case**

⇒ Each migration flow will be converted to $(Q + 1)$ -quantiles

⇒ $A_{ij} = 0$ indicates relatively low number of migrants, $A_{ij} = Q$ indicates high migration

- We assume $Q = K$ (i.e., as many moments as symbols)



Real-life dataset (II): UN migration data - Graph Generation

- Consider a single link $(i, j) \Rightarrow$ How can we estimate $p_l = P[A_{ij} = l]$?
- We have the following system of equations:

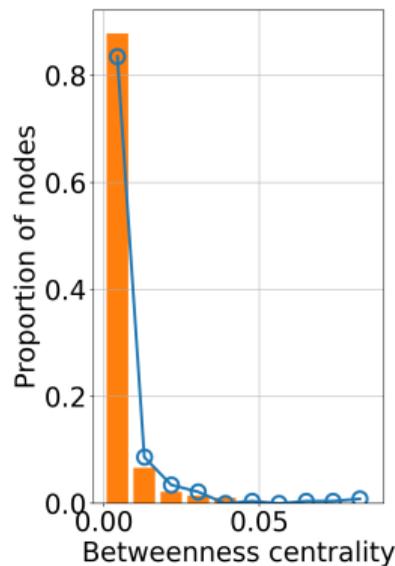
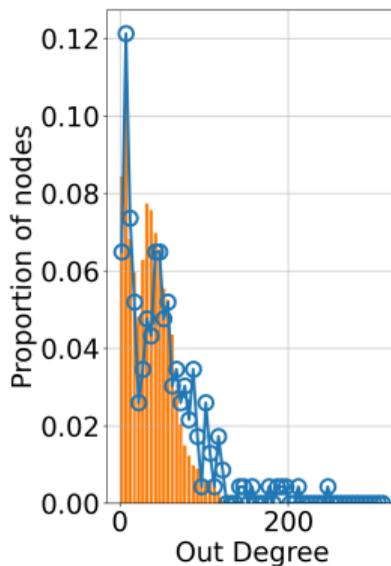
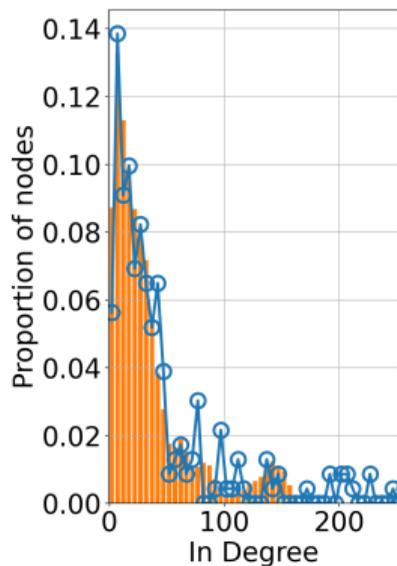
$$\left\{ \begin{array}{l} p_0 + p_1 + \dots + p_K = \mu_0 \\ 0p_0 + 1p_1 + \dots + Kp_K = \mu_1 \\ 0^2p_0 + 1^2p_1 + \dots + K^2p_K = \mu_2 \\ \vdots \\ 0^Kp_0 + 1^Kp_1 + \dots + K^Kp_K = \mu_K \end{array} \right. \Leftrightarrow \mathbf{V}\mathbf{p} = \boldsymbol{\mu} \quad (2)$$

- \mathbf{V} is a Vandermonde matrix of the possible symbols (in this case $0, 1, \dots, Q = K$)



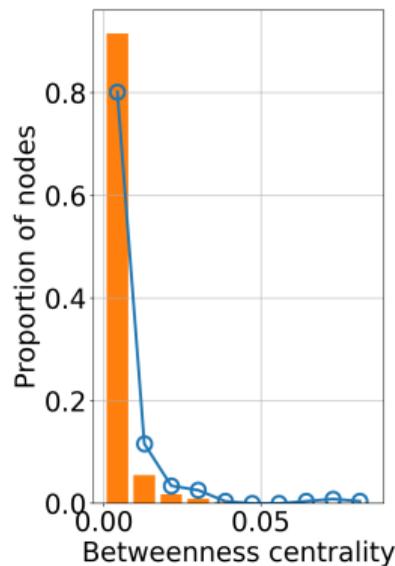
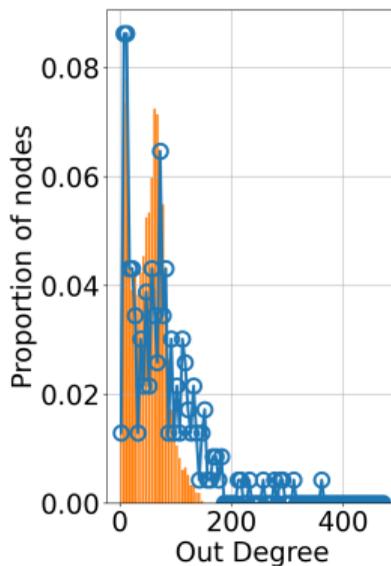
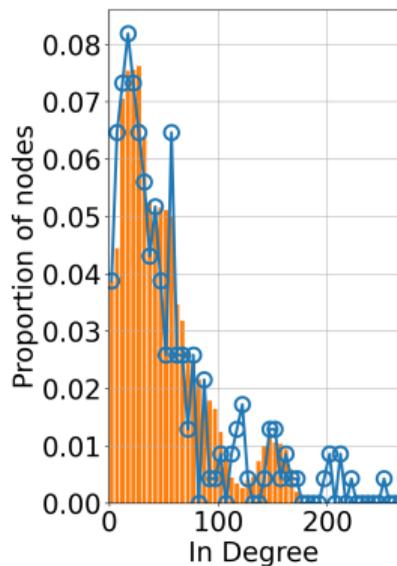
Real-life dataset (II): UN migration data - Graph Generation

- **Simulations:** For each pair of nodes estimate \mathbf{p} , generate 100 graphs and compute:
 - Degree distribution
 - Nodes' betweenness centrality
- Great fit for $Q = 2$



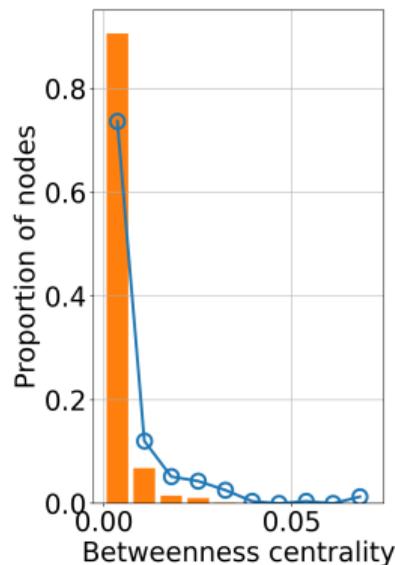
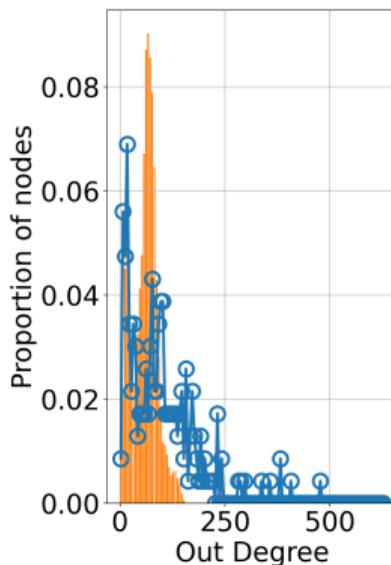
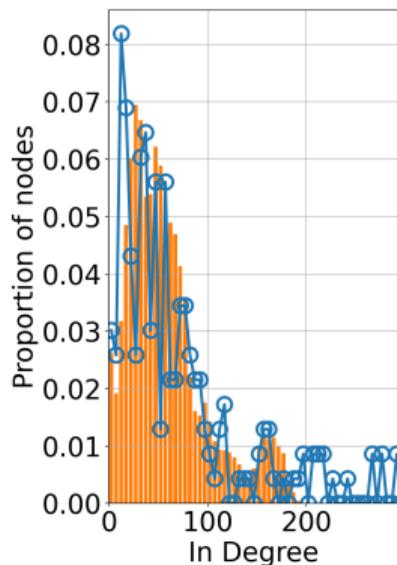
Real-life dataset (II): UN migration data - Graph Generation

- **Simulations:** For each pair of nodes estimate \mathbf{p} , generate 100 graphs and compute:
 - Degree distribution
 - Nodes' betweenness centrality
- Great fit for $Q = 2, 3$.



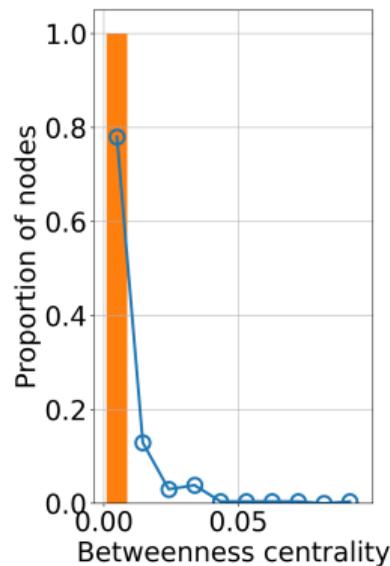
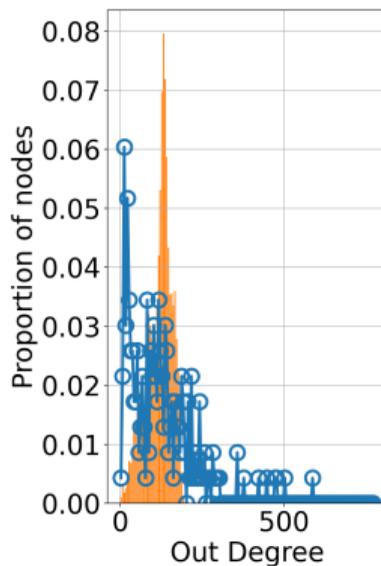
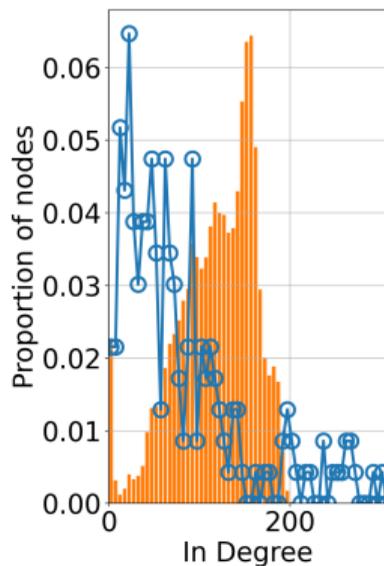
Real-life dataset (II): UN migration data - Graph Generation

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Real-life dataset (II): UN migration data - Graph Generation

- **Simulations:** For each pair of nodes estimate \mathbf{p} , generate 100 graphs and compute:
 - Degree distribution
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- Great fit for $Q = 2, 3$. Not so good for $Q = 4$. And as we add more symbols...



Limitations and Future Work

- Estimating several moments is challenging (unless we have a large graph)
- ⇒ How can we estimate a distribution from just a few moments?



Limitations and Future Work

- Estimating several moments is challenging (unless we have a large graph)
⇒ How can we estimate a distribution from just a few moments?
- Estimating a distribution per-link does not scale
⇒ Grouping nodes should help. What's the impact on the estimation?



Thanks!

Questions?

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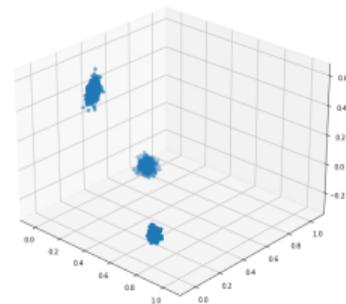
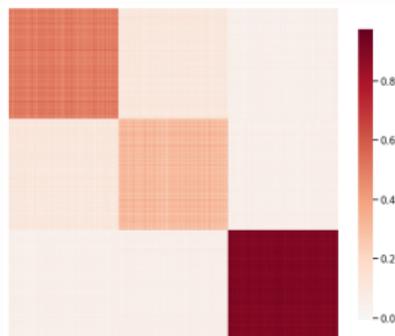
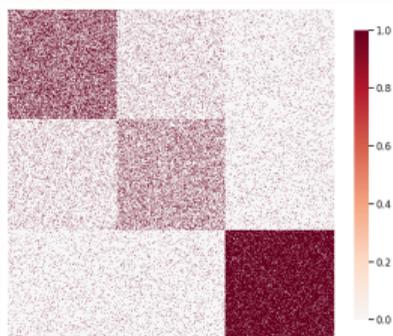
🌐 <https://github.com/git-artes/>



Embedding an SBM graph

- **Ex:** SBM with $N_v = 1500$, $Q = 3$ and mixing parameters

$$\boldsymbol{\alpha} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}, \quad \boldsymbol{\Pi} = \begin{bmatrix} 0.5 & 0.1 & 0.05 \\ 0.1 & 0.3 & 0.05 \\ 0.05 & 0.05 & 0.9 \end{bmatrix}$$



- Sample adjacency \mathbf{A} (left), $\hat{\mathbf{X}}_{LS} \hat{\mathbf{X}}_{LS}^T$ (center), rows of $\hat{\mathbf{X}}_{LS}$ (right)
- Use embeddings to bring to bear geometric methods of analysis



Ambiguity

- **Q:** Is the solution to ASE unique? Nope, inner-products are rotation invariant

$$\mathbf{P} = \mathbf{XW}(\mathbf{XW})^\top = \mathbf{XX}^\top, \quad \mathbf{WW}^\top = \mathbf{I}_d$$

⇒ RDPG embedding problem is identifiable modulo rotations



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- a transformation with *any invertible* matrix $\mathbf{W} \in \mathbb{R}^{d \times d}$ will result in the same $\mathbf{M}[k]$.
undirected (W)RDPG: \mathbf{W} orthonormal matrix
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- \mathbf{W} is necessarily orthonormal by enforcing $\mathbf{X}^l[k]$ and $\mathbf{X}^r[k]$ with orthogonal columns



Weighted RDPG

- Vanilla RDPG require $0 \leq \mathbf{x}_i \mathbf{x}_i^\top \leq 1$. Is any sequence $\mathbf{M}[k]$ valid in WRDPG?
 - Certainly not! E.g. $M_{ij}[k] = -1$ for all k cannot be correct



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 - Certainly not! E.g. $M_{ij}[k] = -1$ for all k cannot be correct
- A sequence $\{m[k]\}_{k \geq 0}$ is an **admissible moment sequence** if $m[0] = 1$ and the matrix

$$\mathbf{B} = \begin{pmatrix} m[0] & m[1] & m[2] & \dots & m[p] \\ m[1] & m[2] & m[3] & \dots & m[p+1] \\ m[2] & m[3] & m[4] & \dots & m[p+3] \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ m[p] & m[p+1] & m[p+2] & \dots & m[2p] \end{pmatrix}$$

is positive-semidefinite for all $p \geq 0$

$\Rightarrow M_{ij}[k]$ has to be an admissible moment sequence for all i, j

