

# PageRank: Ranking of nodes in graphs

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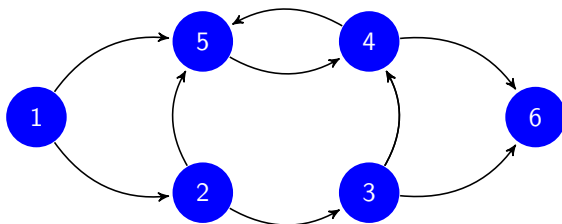
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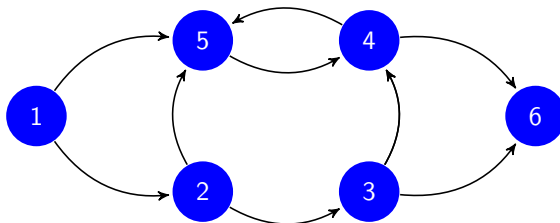
Ranking of nodes in graphs: Random walk

Ranking of nodes in graphs: Probability propagation



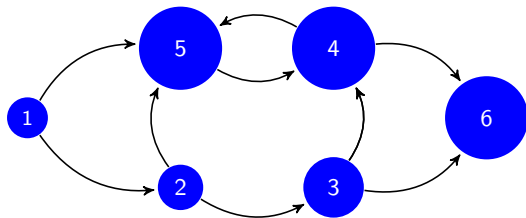
- ▶ **Graph**  $\Rightarrow$  A set of  $V$  of vertices or nodes  $j = 1, \dots, J$   
 $\Rightarrow$  Connected by a set of edges  $E$  defined as ordered pairs  $(i, j)$
- ▶ In figure  $\Rightarrow$  Nodes are  $V = \{1, 2, 3, 4, 5, 6\}$   
 $\Rightarrow$  Edges  $E = \{(1, 2), (1, 5), (2, 3), (2, 5), (3, 4), \dots$   
 $(3, 6), (4, 5), (4, 6), (5, 4)\}$
- ▶ **Ex. 1:** Websites and hyperlinks  $\Rightarrow$  World Wide Web (WWW)
- ▶ **Ex. 2:** People and friendship  $\Rightarrow$  Social network

# How well connected nodes are?



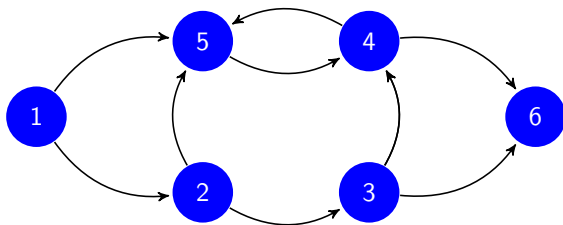
- ▶ **Q:** Which node is the most connected? **A:** Define most connected  
⇒ Can define “most connected” in different ways
- ▶ Two important **connectivity indicators**
  - 1) How many links point to a node (outgoing links irrelevant)
  - 2) How important are the links that point to a node
- ▶ **Node rankings** to measure website relevance, social influence

- ▶ **Key insight:** There is information in the **structure of the network**
- ▶ Knowledge is distributed through the network
  - ⇒ The network (not the nodes) knows the rankings
- ▶ Idea exploited by Google's PageRank<sup>©</sup> to rank webpages
  - ... by social scientists to study trust & reputation in social networks
  - ... by ISI to rank scientific papers, transactions & magazines ...



- ▶ No one points to 1
- ▶ Only 1 points to 2
- ▶ Only 2 points to 3, but 2 more important than 1
- ▶ 4 as high as 5 with less links
- ▶ Links to 5 have lower rank
- ▶ Same for 6

- ▶ Graph  $G = (V, E) \Rightarrow$  vertices  $V = \{1, 2, \dots, J\}$  and edges  $E$



- ▶ Outgoing neighborhood of  $i$  is the set of nodes  $j$  to which  $i$  points

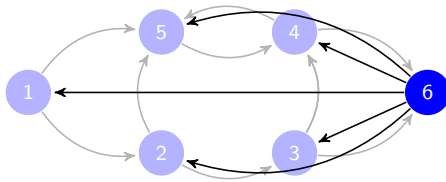
$$n(i) := \{j : (i, j) \in E\}$$

- ▶ Incoming neighborhood,  $n^{-1}(i)$  is the set of nodes that point to  $i$ :

$$n^{-1}(i) := \{j : (j, i) \in E\}$$

- ▶ Strongly connected  $G \Rightarrow$  directed path joining any pair of nodes

- ▶ **Agent  $A$**  chooses node  $i$ , e.g., web page, at random for initial visit
- ▶ **Next visit randomly** chosen between links **in the neighborhood  $n(i)$** 
  - ⇒ All neighbors chosen with **equal probability**
- ▶ If reach a dead end because node  $i$  has no neighbors
  - ⇒ Chose next visit at random equiprobably among all nodes
- ▶ Redefine graph  $\mathcal{G} = (V, E)$  adding edges from dead ends to all nodes
  - ⇒ Restrict attention to connected (modified) graphs



- ▶ **Rank of node  $i$**  is the average number of visits of agent  $A$  to  $i$

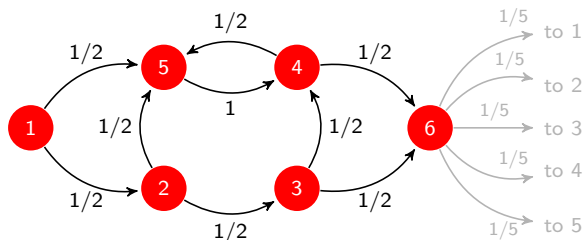
# Equiprobable random walk

- ▶ Formally, let  $A_n$  be the node visited at time  $n$
- ▶ Define transition probability  $P_{ij}$  from node  $i$  into node  $j$

$$P_{ij} := P(A_{n+1} = j \mid A_n = i)$$

- ▶ Next visit equiprobable among  $i$ 's  $N_i := |n(i)|$  neighbors

$$P_{ij} = \frac{1}{|n(i)|} = \frac{1}{N_i}, \quad \text{for all } j \in n(i)$$



- ▶ Still have a graph
- ▶ But also a MC
- ▶ Red (not blue) circles



- ▶ **Def:** Rank  $r_i$  of  $i$ -th node is the **time average of number of visits**

$$r_i := \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1}^n \mathbb{I}\{A_m = i\}$$

⇒ Define vector of ranks  $\mathbf{r} := [r_1, r_2, \dots, r_J]^T$

- ▶ Rank  $r_i$  can be approximated by average  $r_{ni}$  at time  $n$

$$r_{ni} := \frac{1}{n} \sum_{m=1}^n \mathbb{I}\{A_m = i\}$$

⇒ Since  $\lim_{n \rightarrow \infty} r_{ni} = r_i$ , it holds  $r_{ni} \approx r_i$  for  $n$  sufficiently large

⇒ Define vector of approximate ranks  $\mathbf{r}_n := [r_{n1}, r_{n2}, \dots, r_{nJ}]^T$

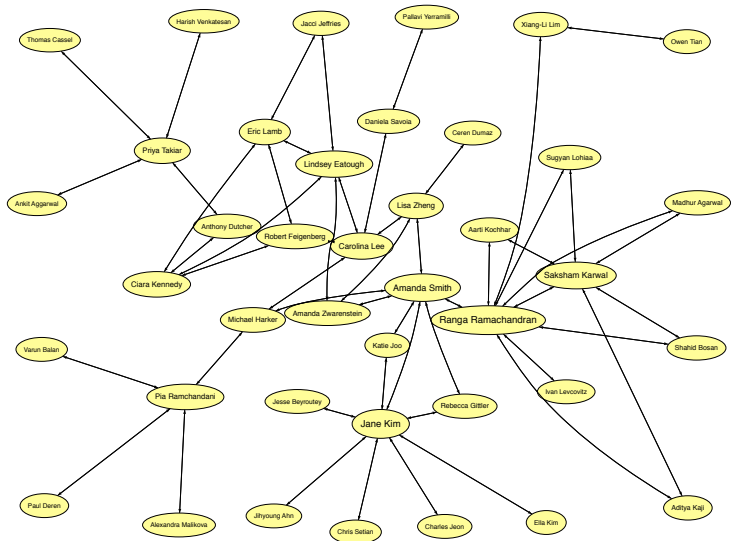
- ▶ If modified graph is connected, **rank independent of initial visit**

**Output** : Vector  $\mathbf{r}(i)$  with ranking of node  $i$   
**Input** : Scalar  $n$  indicating maximum number of iterations  
**Input** : Vector  $N(i)$  containing number of neighbors of  $i$   
**Input** : Matrix  $\mathbf{N}(i,j)$  containing indices  $j$  of neighbors of  $i$

```
 $m = 1$ ;  $\mathbf{r} = \text{zeros}(J,1)$ ; % Initialize time and ranks  
 $A_0 = \text{random}(\text{'unid'}, J)$ ; % Draw first visit uniformly at random  
while  $m < n$  do  
    |  $\text{jump} = \text{random}(\text{'unid'}, N_{A_{m-1}})$ ; % Neighbor uniformly at random  
    |  $A_m = \mathbf{N}(A_{m-1}, \text{jump})$ ; % Jump to selected neighbor  
    |  $\mathbf{r}(A_m) = \mathbf{r}(A_m) + 1$ ; % Update ranking for  $A_m$   
    |  $m = m + 1$ ;  
end  
 $\mathbf{r} = \mathbf{r}/n$ ; % Normalize by number of iterations  $n$ 
```

- ▶ Asked probability students about homework collaboration
- ▶ Created (crude) graph of the social network of students in the class
  - ⇒ Used ranking algorithm to understand connectedness
- ▶ **Ex:** I want to know how well students are coping with the class
  - ⇒ Best to ask people with higher connectivity ranking
- ▶ 2009 data from “UPenn’s ECE440”

# Ranked class graph



- ▶ Recall  $\mathbf{r}$  is vector of ranks and  $\mathbf{r}_n$  of rank iterates
- ▶ By definition  $\lim_{n \rightarrow \infty} \mathbf{r}_n = \mathbf{r}$ . How fast  $\mathbf{r}_n$  converges to  $\mathbf{r}$  ( $\mathbf{r}$  given)?
- ▶ Can measure by  $\ell_2$  distance between  $\mathbf{r}$  and  $\mathbf{r}_n$

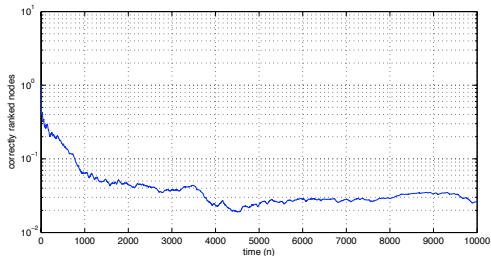
$$\zeta_n := \|\mathbf{r} - \mathbf{r}_n\|_2 = \left( \sum_{i=1}^J (r_{ni} - r_i)^2 \right)^{1/2}$$

- ▶ If interest is only on **highest ranked nodes**, e.g., a web search
  - ⇒ Denote  $r^{(i)}$  as the index of the  $i$ -th highest ranked node
  - ⇒ Let  $r_n^{(i)}$  be the index of the  $i$ -th highest ranked node at time  $n$
- ▶ **First element wrongly ranked at time  $n$**

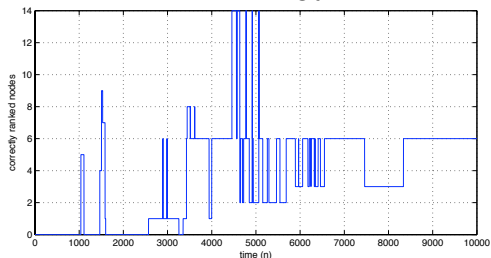
$$\xi_n := \arg \min_i \{r^{(i)} \neq r_n^{(i)}\}$$

# Evaluation of convergence metrics

## Distance



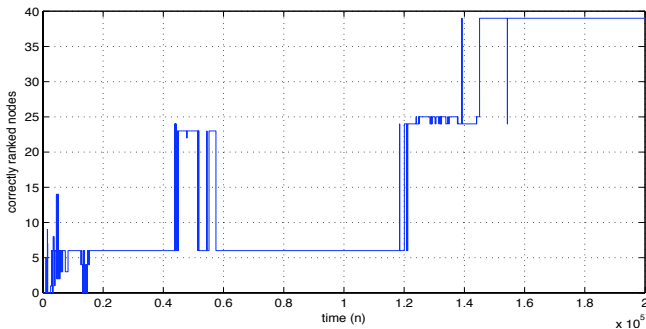
## First element wrongly ranked



- ▶ Distance close to  $10^{-2}$  in  $\approx 5 \times 10^3$  iterations
- ▶ **Bad:** Two highest ranks in  $\approx 4 \times 10^3$  iterations
- ▶ **Awful:** Six best ranks in  $\approx 8 \times 10^3$  iterations
- ▶ **(Very)** slow convergence

# When does this algorithm converge?

- ▶ Cannot confidently claim convergence until  $10^5$  iterations
  - ⇒ Beyond particular case, **slow convergence inherent to algorithm**



- ▶ Example has 40 nodes, want to use in network with  $10^9$  nodes!
  - ⇒ **Leverage properties of MCs to obtain a faster algorithm**

Ranking of nodes in graphs: Random walk

Ranking of nodes in graphs: Probability propagation



- ▶ Recall definition of rank  $\Rightarrow r_i := \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1}^n \mathbb{I}\{A_m = i\}$
- ▶ Rank is time average of number of state visits in a MC  
 $\Rightarrow$  Can be as well obtained from limiting probabilities
- ▶ Recall transition probabilities  $\Rightarrow P_{ij} = \frac{1}{N_i}$ , for all  $j \in n(i)$
- ▶ Stationary distribution  $\boldsymbol{\pi} = [\pi_1, \pi_1, \dots, \pi_J]^T$  solution of
$$\pi_i = \sum_{j \in n^{-1}(i)} P_{ji} \pi_j = \sum_{j \in n^{-1}(i)} \frac{\pi_j}{N_j} \quad \text{for all } i$$
  
 $\Rightarrow$  Plus normalization equation  $\sum_{i=1}^J \pi_i = 1$
- ▶ As per **ergodicity** of MC (strongly connected G)  $\Rightarrow \mathbf{r} = \boldsymbol{\pi}$

- ▶ As always, can define matrix  $\mathbf{P}$  with elements  $P_{ij}$

$$\pi_i = \sum_{j \in n^{-1}(i)} P_{ji} \pi_j = \sum_{j=1}^J P_{ji} \pi_j \quad \text{for all } i$$

- ▶ Right hand side is just definition of a matrix product leading to

$$\boldsymbol{\pi} = \mathbf{P}^T \boldsymbol{\pi}, \quad \boldsymbol{\pi}^T \mathbf{1} = 1$$

⇒ Also added normalization equation

- ▶ **Idea:** solve **system of linear equations** or **eigenvalue problem** on  $\mathbf{P}^T$ 
  - ⇒ Requires matrix  $\mathbf{P}$  available at a central location
  - ⇒ **Computationally costly** (sparse matrix  $\mathbf{P}$  with  $10^{18}$  entries)

# What are limit probabilities?

- ▶ Let  $p_i(n)$  denote probability of agent  $A$  visiting node  $i$  at time  $n$

$$p_i(n) := P(A_n = i)$$

- ▶ Probabilities at time  $n + 1$  and  $n$  can be related

$$P(A_{n+1} = i) = \sum_{j \in n^{-1}(i)} P(A_{n+1} = i | A_n = j) P(A_n = j)$$

- ▶ Which is, of course, probability propagation in a MC

$$p_i(n+1) = \sum_{j \in n^{-1}(i)} P_{ji} p_j(n)$$

- ▶ By definition limit probabilities are (let  $\mathbf{p}(n) = [p_1(n), \dots, p_J(n)]^T$ )

$$\lim_{n \rightarrow \infty} \mathbf{p}(n) = \boldsymbol{\pi} = \mathbf{r}$$

⇒ Compute ranks from limit of propagated probabilities

- ▶ Can also write probability propagation in matrix form

$$p_i(n+1) = \sum_{j \in n^{-1}(i)} P_{ji} p_j(n) = \sum_{j=1}^J P_{ji} p_j(n) \quad \text{for all } i$$

- ▶ Right hand side is just definition of a matrix product leading to

$$\mathbf{p}(n+1) = \mathbf{P}^T \mathbf{p}(n)$$

- ▶ **Idea:** can approximate rank by large  $n$  probability distribution

$$\Rightarrow \mathbf{r} = \lim_{n \rightarrow \infty} \mathbf{p}(n) \approx \mathbf{p}(n) \text{ for } n \text{ sufficiently large}$$

- ▶ Algorithm is just a recursive matrix product, a power iteration

**Output** : Vector  $\mathbf{r}(i)$  with ranking of node  $i$

**Input** : Scalar  $n$  indicating maximum number of iterations

**Input** : Matrix  $\mathbf{P}$  containing transition probabilities

```
 $m = 1;$  % Initialize time
```

```
 $\mathbf{r} = (1/J)\mathbf{ones}(J,1);$  % Initial distribution uniform across all nodes
```

```
while  $m < n$  do
```

```
     $\mathbf{r} = \mathbf{P}^T \mathbf{r};$  % Probability propagation
```

```
     $m = m + 1;$ 
```

```
end
```

- ▶ **Q:** Why does the random walk converge so slow?
- ▶ **A:** Need to register a large number of agent visits to every state  
**Ex:** 40 nodes, say 100 visits to each  $\Rightarrow 4 \times 10^3$  iters.
- ▶ **Smart idea:** Unleash a large number of agents  $K$

$$r_i = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1}^n \frac{1}{K} \sum_{k=1}^K \mathbb{I}\{A_{km} = i\}$$

- ▶ Visits are now spread over **time and space**
  - $\Rightarrow$  Converges “ $K$  times faster”
  - $\Rightarrow$  But haven’t changed computational cost

- ▶ **Q:** What happens if we unleash infinite number of agents  $K$ ?

$$r_i = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1}^n \lim_{K \rightarrow \infty} \frac{1}{K} \sum_{k=1}^K \mathbb{I}\{A_{km} = i\}$$

- ▶ Using law of large numbers and expected value of indicator function

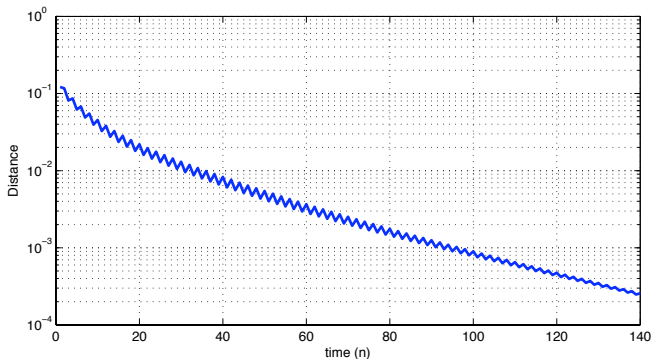
$$r_i = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1}^n \mathbb{E}[\mathbb{I}\{A_m = i\}] = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1}^n \mathbb{P}(A_m = i)$$

- ▶ Graph walk is an ergodic MC, then  $\lim_{m \rightarrow \infty} \mathbb{P}(A_m = i)$  exists, and

$$r_i = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1}^n p_i(m) = \lim_{n \rightarrow \infty} p_i(n)$$

⇒ **Probability propagation**  $\approx$  **Unleashing infinitely many agents**

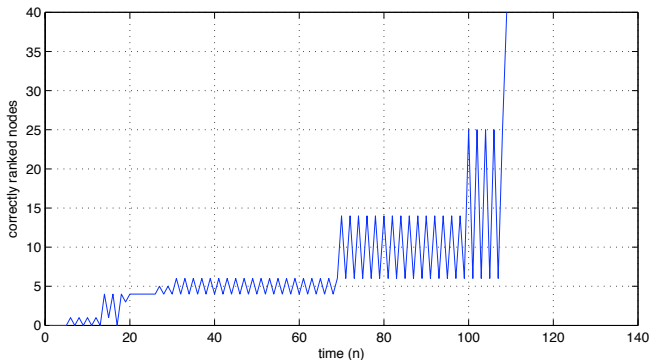
- ▶ Initialize with uniform probability distribution  $\Rightarrow \mathbf{p}(0) = (1/J)\mathbf{1}$   
 $\Rightarrow$  Plot distance between  $\mathbf{p}(n)$  and  $\mathbf{r}$



- ▶ Distance is  $10^{-2}$  in  $\approx 30$  iters.,  $10^{-4}$  in  $\approx 140$  iters.  
 $\Rightarrow$  Convergence two orders of magnitude faster than random walk



- ▶ Rank of highest ranked node that is wrongly ranked by time  $n$



- ▶ **Not bad:** All nodes correctly ranked in 120 iterations
- ▶ **Good:** Ten best ranks in 70 iterations
- ▶ **Great:** Four best ranks in 20 iterations

- ▶ Nodes want to compute their rank  $r_i$ 
  - ⇒ Can **communicate with neighbors** only (incoming + outgoing)
  - ⇒ Access to **neighborhood information** only

- ▶ Recall probability update

$$p_i(n+1) = \sum_{j \in n^{-1}(i)} P_{ji} p_j(n) = \sum_{j \in n^{-1}(i)} \frac{1}{N_j} p_j(n)$$

⇒ **Uses local information only**

- ▶ **Distributed algorithm.** Nodes keep local rank estimates  $r_i(n)$ 
  - ▶ **Receive** rank (probability) estimates  $r_j(n)$  from neighbors  $j \in n^{-1}(i)$
  - ▶ Update local rank estimate  $r_i(n+1) = \sum_{j \in n^{-1}(i)} r_j(n) / N_j$
  - ▶ **Communicate** rank estimate  $r_i(n+1)$  to outgoing neighbors  $j \in n(i)$
- ▶ **Only need to know the number of neighbors of my neighbors**

- ▶ Can communicate with neighbors only (incoming + outgoing)
  - ⇒ But **cannot access neighborhood information**
  - ⇒ Pass agent ('hot potato') around
- ▶ Local rank estimates  $r_i(n)$  and counter with number of visits  $V_i$
- ▶ Algorithm run by node  $i$  at time  $n$

**if** *Agent received from neighbor* **then**

$V_i = V_i + 1$

Choose random neighbor

Send agent to chosen neighbor

**end**

$n = n + 1$ ;  $r_i(n) = V_i/n$ ;

- ▶ Speed up convergence by generating many agents to pass around

- ▶ **Random walk (RW) implementation**

- ⇒ Most secure. No information shared with other nodes
- ⇒ Implementation can be distributed
- ⇒ Convergence exceedingly slow

- ▶ **System of linear equations**

- ⇒ Least security. Graph in central server
- ⇒ Distributed implementation not clear
- ⇒ Convergence not an issue
- ⇒ But computationally costly to obtain approximate solutions

- ▶ **Probability propagation**

- ⇒ Somewhat secure. Information shared with neighbors only
- ⇒ Implementation can be distributed
- ⇒ Convergence rate acceptable (orders of magnitude faster than RW)

- ▶ Graph, nodes and edges
- ▶ Connectivity indicators
- ▶ Node ranking
- ▶ Google's PageRank
- ▶ Node's neighborhood
- ▶ Strong connectivity
- ▶ Random walk on a graph
- ▶ Long-run fraction of state visits
- ▶ Ranking algorithm
- ▶ Convergence metrics
- ▶ Computational cost
- ▶ Probability propagation
- ▶ Power method
- ▶ Distributed algorithm
- ▶ Security