

Online Graph Learning under Smoothness Priors

Seyed Saman Saboksayr

Dept. of Electrical and Computer Engineering

University of Rochester

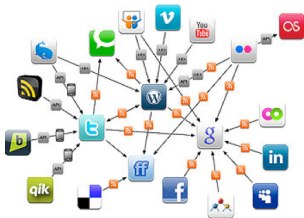
Email: ssaboksa@ur.rochester.edu

Co-authors: Gonzalo Mateos and Mujdat Cetin

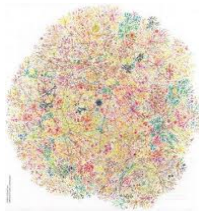
Acknowledgement: NSF awards CCF-1750428, CCF-1934962 and ECCS-1809356

EUSIPCO, August 23-27, 2021

Online social media



Internet



Clean energy and grid analytics



- ▶ **Network as graph** $\mathcal{G}(\mathcal{V}, \mathcal{E})$: encode pairwise relationships
- ▶ **Desiderata**: Process, analyze and learn from **network data** [Kolaczyk'09]
⇒ Use \mathcal{G} to study **graph signals**, **data** associated with **nodes** in \mathcal{V}
- ▶ **Ex**: Opinion profile, buffer congestion levels, functional brain connectivity
- ▶ **Q**: What about **streaming** data from (possibly) **dynamic** networks?

- ▶ Network **topology inference** from nodal observations [Kolaczyk'09]
 - ▶ Partial correlations and conditional dependence [Dempster'74]
 - ▶ Sparsity [Friedman et al'07] and consistency [Meinshausen-Buhlmann'06]
- ▶ Key in neuroscience [Kassam et al'13] and financial market analytics [Palomar et al'20]
- ▶ Noteworthy **GSP**-based approaches
 - ▶ Graphical models [Egilmez et al'16], [Rabbat'17], [Kumar et al'19], ...
 - ▶ Smooth signals [Dong et al'15], [Kalofolias'16], [Sardellitti et al'17], ...
 - ▶ Streaming data [Shafipour et al'18], [Natali et al'20], [Saboksayr et al'21], ...
- ▶ **Our contribution:** Graph learning from **streaming** signals
 - ⇒ Topology inference via convergent online **proximal gradient (PG)** iterations

Setup

- ▶ Sparse network \mathcal{G} with unknown adjacency matrix \mathbf{W} (or \mathbf{W}_t in dynamic setting)
- ▶ Observe streaming smooth signals $\{\mathbf{x}_t\}_{t=1}^T$ defined on \mathcal{G}
- ▶ Total variation (smoothness measure) of signal \mathbf{x} with respect to $\mathbf{L} = \mathbf{D} - \mathbf{W}$

$$\text{TV}(\mathbf{x}) := \mathbf{x}^\top \mathbf{L} \mathbf{x} = \frac{1}{2} \sum_{i \neq j} W_{ij} (x_i - x_j)^2$$

Problem statement

Given a set $\mathcal{X} = \{\mathbf{x}_t\}_{t=1}^T$ of graph signal observations acquired at time t , learn an undirected graph $\mathcal{G}(\mathcal{V}, \mathcal{E}, \mathbf{W})$ such that the observations in \mathcal{X} are smooth on \mathcal{G} .

- ▶ Given \mathcal{X} one can form the data matrix $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_T] \in \mathbb{R}^{N \times T}$

⇒ A link between smoothness and sparsity (considering $\mathbf{Z} \in \mathbb{R}_+^{N \times N}$ as **Euclidean-distance matrix**)

$$\sum_{t=1}^T \text{TV}(\mathbf{x}_t) = \text{trace}(\mathbf{X}^\top \mathbf{L} \mathbf{X}) = \frac{1}{2} \|\mathbf{W} \circ \mathbf{Z}\|_1$$

- ▶ Framework for learning graphs under a **smoothness prior** [Kalofolias'16]

$$\min_{\mathbf{W}} \|\mathbf{W} \circ \mathbf{Z}\|_1 + g(\mathbf{W}) \quad \text{s. t.} \quad \text{diag}(\mathbf{W}) = \mathbf{0}, W_{ij} = W_{ji} \geq 0, i \neq j$$

⇒ Convex objective function $g(\mathbf{W})$ encodes assumptions about the network \mathcal{G}

⇒ Amenable to the **proximal gradient** method, $\mathcal{O}(N^2)$ complexity per iteration

- **Q: Online** estimation from **streaming** data $\{\mathbf{x}_1, \dots, \mathbf{x}_t, \mathbf{x}_{t+1}, \dots\}$

⇒ At time t solve the time-varying composite optimization

$$\mathbf{w}_t^* \in \underset{\mathbf{w}}{\operatorname{argmin}} F_t(\mathbf{w}) := \underbrace{\mathbb{I}\{\mathbf{w} \succeq \mathbf{0}\} + 2\mathbf{w}^\top \mathbf{z}_{1:t}}_{h_t(\mathbf{w})} \underbrace{- \alpha \mathbf{1}^\top \log(\mathbf{S}\mathbf{w}) + \beta 2\|\mathbf{w}\|^2}_{g(\mathbf{w})}.$$

- **Step 1:** Recursively update the **Euclidean-distance** vector via exponential moving average

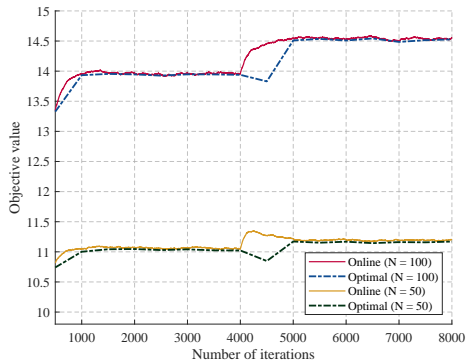
$$\bar{\mathbf{z}}_t = (1 - \gamma)\bar{\mathbf{z}}_{t-1} + \gamma\mathbf{z}_t$$

- **Step 2:** Run a single iteration of the PG algorithm [Madden et al'19]

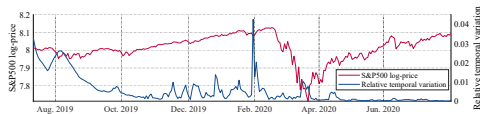
$$\mathbf{w}_{t+1} = \operatorname{prox}_{\mu_t h_t}(\mathbf{w}_t - \mu_t \nabla g(\mathbf{w}_t))$$

⇒ Memory footprint and computational complexity does not grow with t

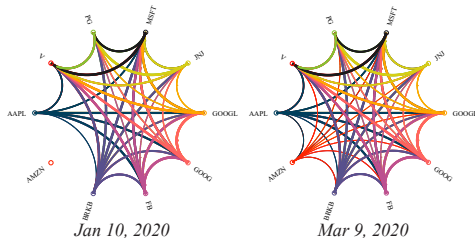
⇒ Guaranteed to converge within a neighborhood of the optimal time-varying batch solution



Mean of objective value as a function of acquired time samples (iteration). Indicates that the proposed method can effectively track its offline counterpart.



The S&P500 log-price per day (red). The daily relative temporal variation of the learned graphs (blue).



The estimated network of the market over two different days.

- ▶ **Our paper:** S. S. Saboksayr, G. Mateos, and M. Cetin, “Online graph learning under smoothness priors” in European Signal Process. Conf. (EUSIPCO), Dublin, Ireland, 2021.
- ▶ **Extended journal paper:** S. S. Saboksayr, G. Mateos, and M. Cetin, “Online discriminative graph learning from multi-class smooth signals,” Signal Processing, vol. 186,p. 108101, 2021.
- ▶ **Session:** Signal Processing over Graphs and Networks (Wednesday, 25 August, 13:30 - 16:30 IST)